

FIG. 1

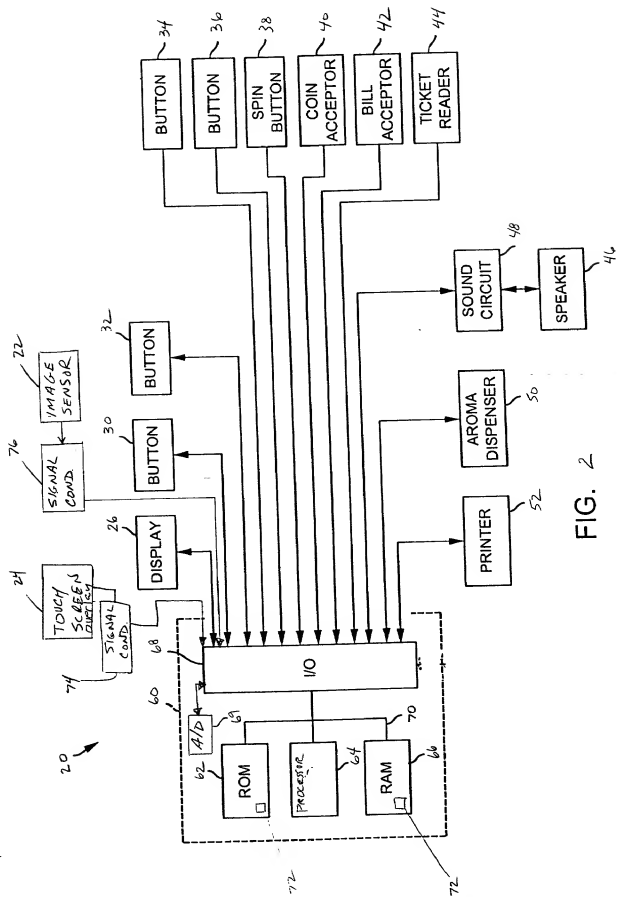


FIG. 2

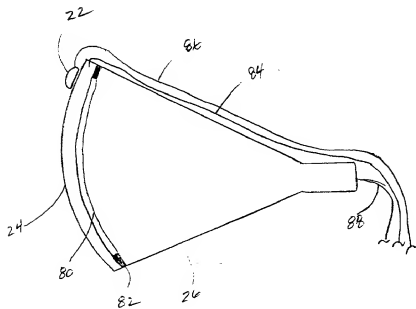
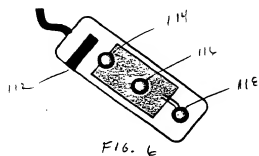
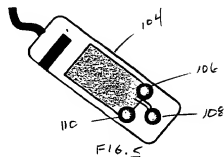
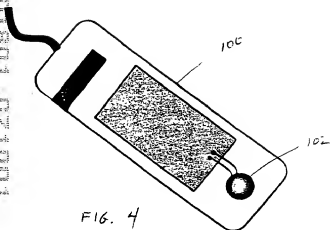


FIG. 3

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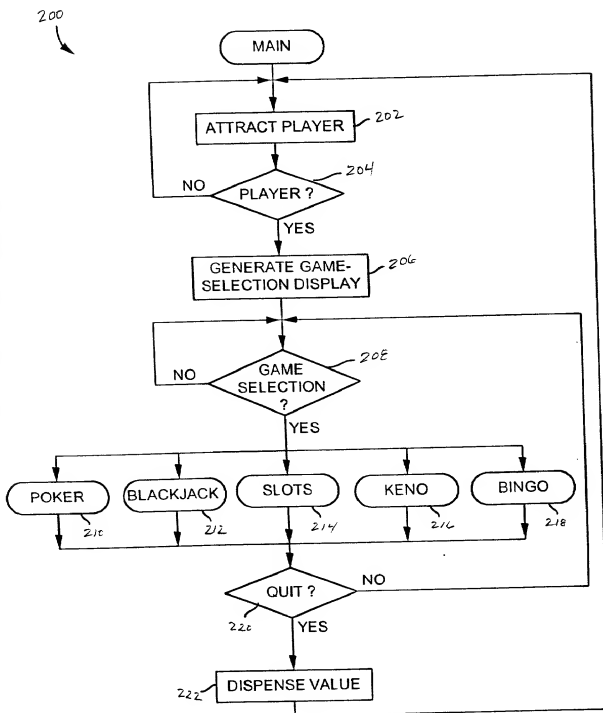


FIG. 7

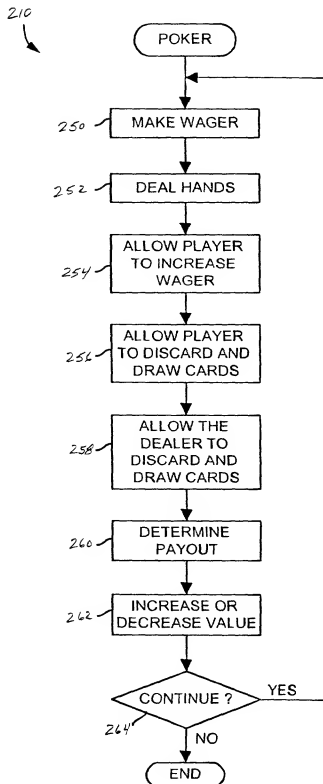


FIG. 8

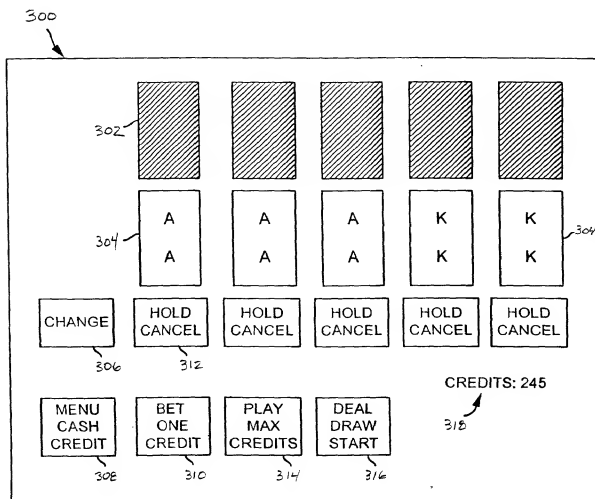


FIG. 9

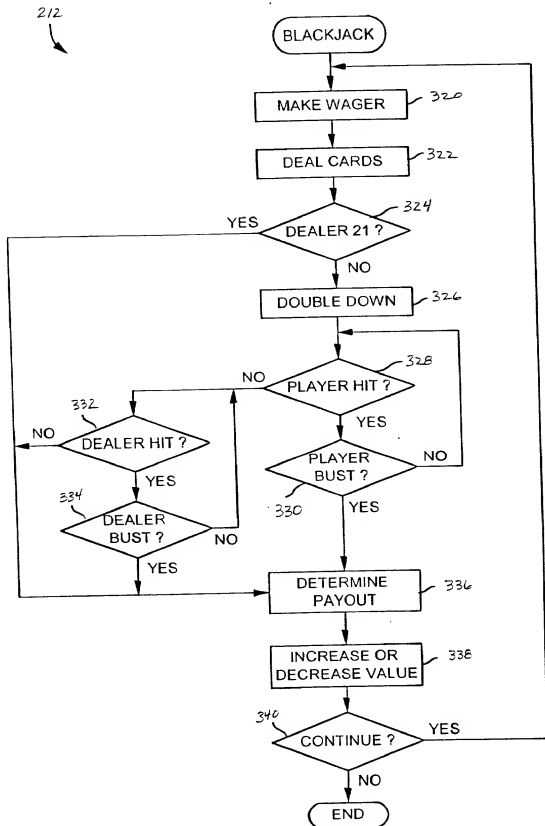


FIG. 10

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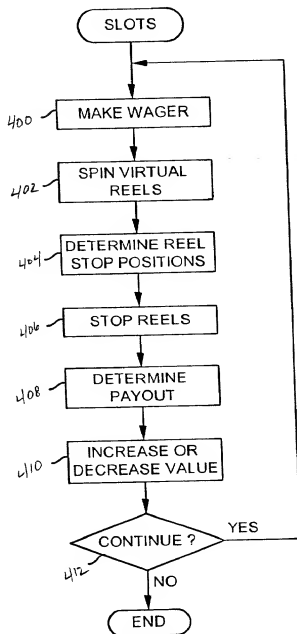


FIG. 11

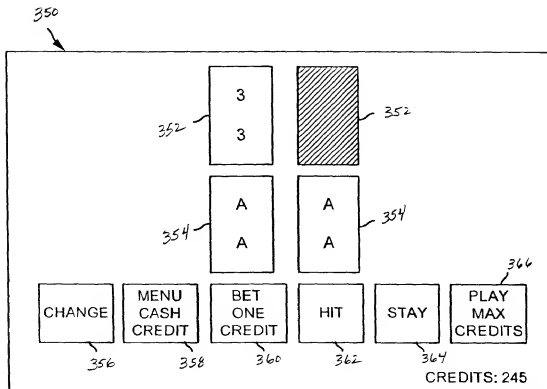


FIG. 12

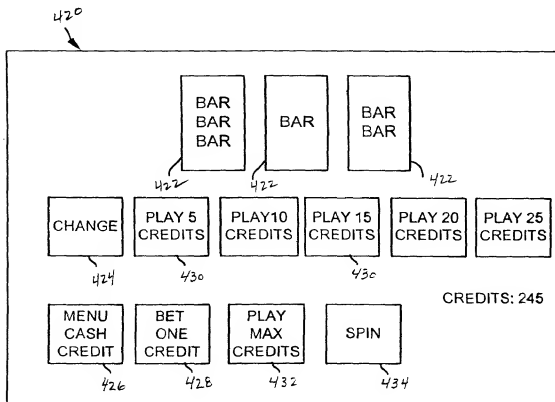


FIG. 13

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↙

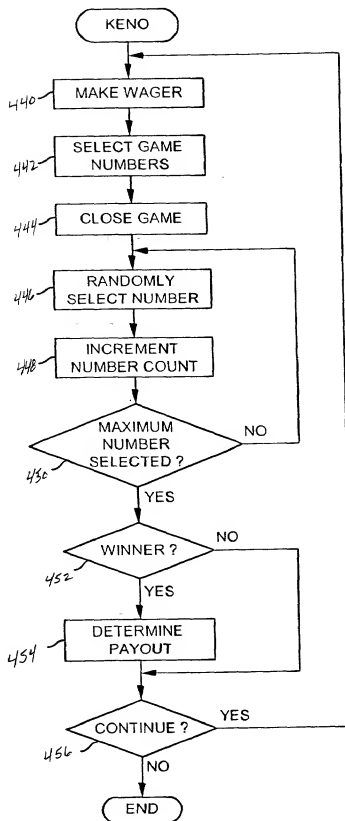


FIG. 14

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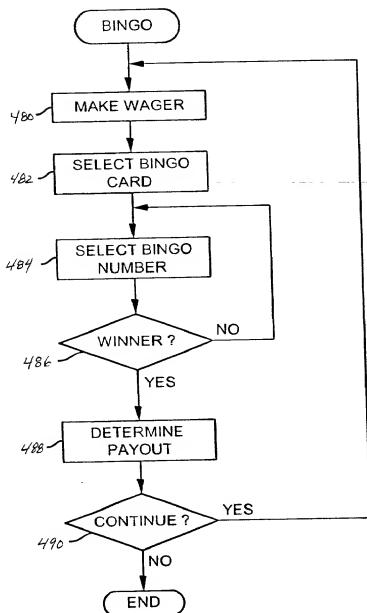


FIG. 15

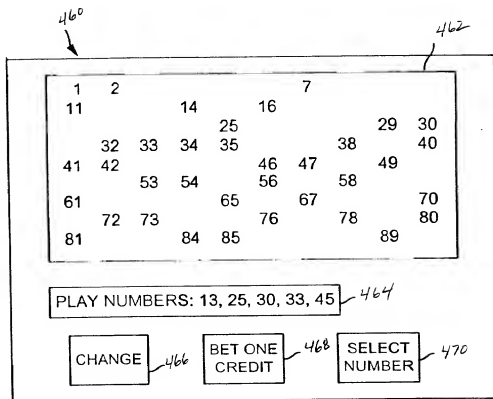


FIG. 16

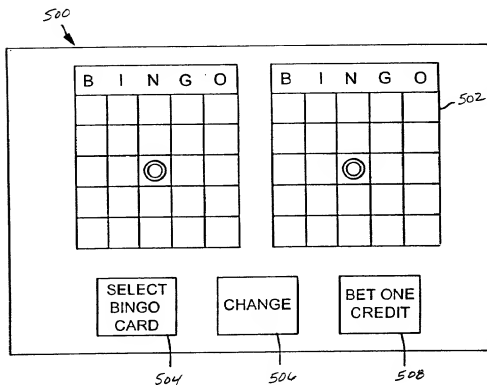


FIG. 17

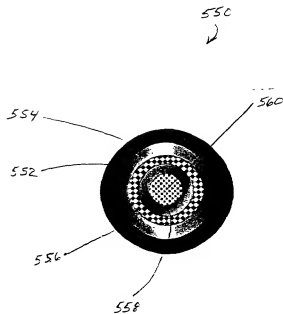


FIG. 18

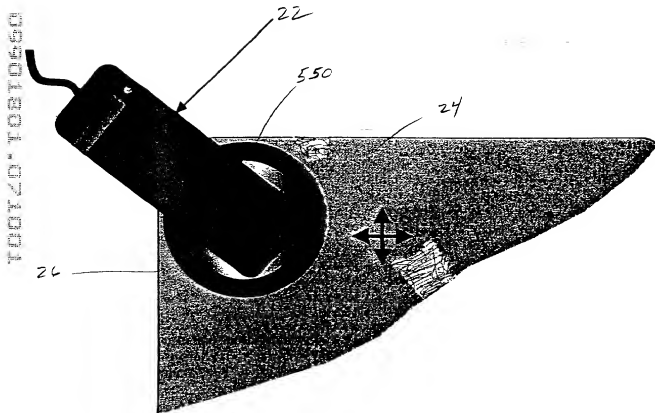


FIG. 19

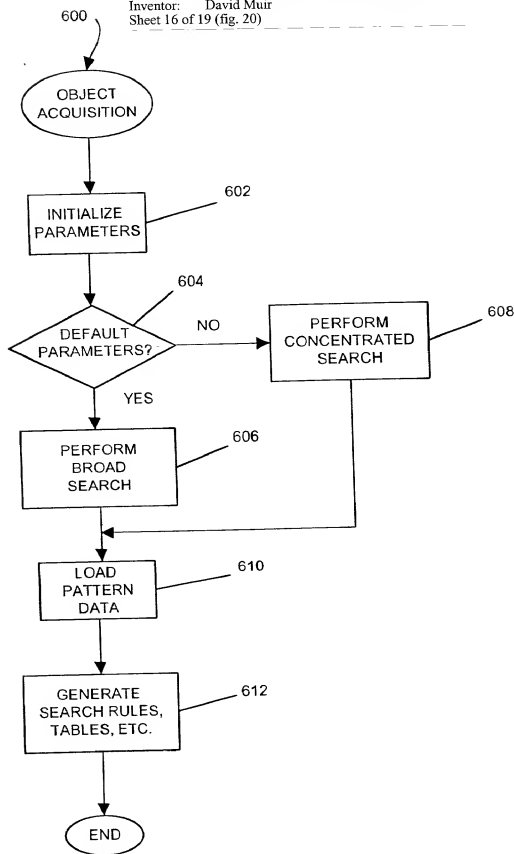


FIG. 20

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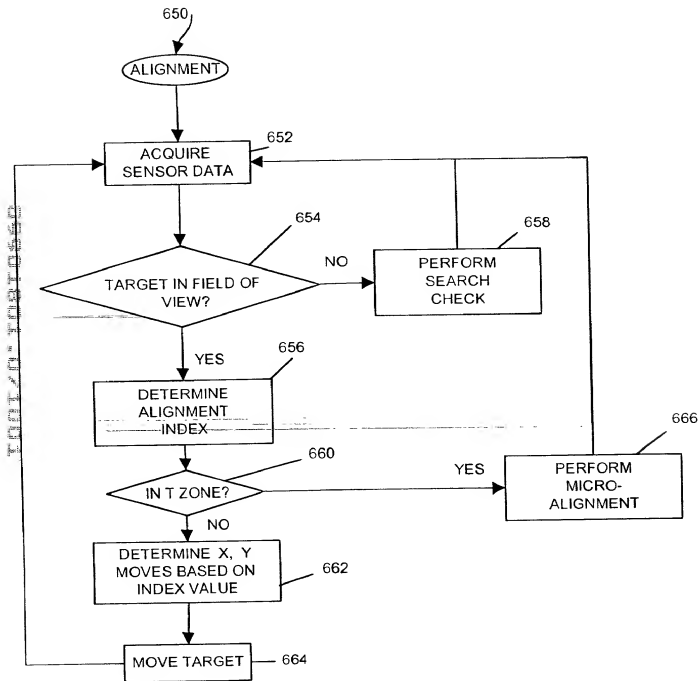


FIG. 21

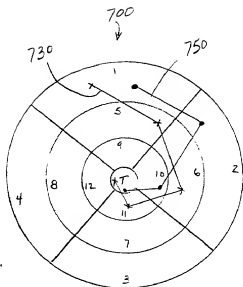


FIG. 22

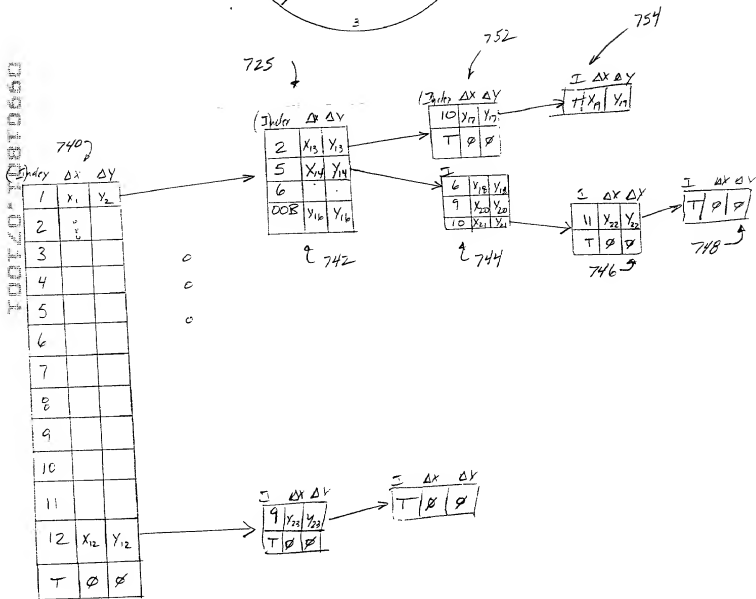


FIG. 23

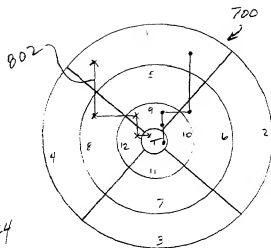


FIG 24

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(J)	Δx	Δy
1	\emptyset	$-Y_1$
2	$-X_1$	\emptyset
3	\emptyset	Y_1
4	X_1	\emptyset
5	\emptyset	$-K_1 Y_1$
6	$-K_1 X_1$	\emptyset
7	\emptyset	$K_1 Y_1$
8	$K_1 X_1$	\emptyset
9	\emptyset	$-K_2 Y_1$
10	$-K_2 X_1$	\emptyset
11	\emptyset	$K_2 Y_1$
12	$K_2 X_1$	\emptyset

where $\emptyset \leq K_2 \leq K_1 \leq 1$

where X_1, Y_1 may be dynamically adjusted

FIG 25